

FOUNDATIONS TO ROBOTICS

Introduction to STEM Robotics

MCK-FDLB-6X6



MINDS-i STEM INTEGRATED ROBOTICS: FOUNDATIONS LAB - 6X6

Introduce students to the foundations of robotics with easy to assemble and modify rovers that emphasize real-world applications. Working collaboratively using the Engineering Design Process, students build and program advanced robots to tackle impressive challenges. As they explore mechanical engineering, electrical engineering and programming, students also analyze the robot's physics, mathematical and scientific elements.

- » 2 lab options: 4 or 6-wheel drive
- » Each lab is one semester (90 hours of curriculum) with seven units, designed for 3-5 students

SPARK AND SUSTAIN STUDENTS' INTEREST IN STEM

MINDS-i Robotics engages students in an energizing STEM learning environment with easy to build, program, and modify robots. Technologically advanced rovers and drones perform impressive real-world tasks that build excitement for STEM careers. The curriculum encourages collaborative problem-solving and the open-source Arduino® C++ programming language fosters endless creativity. With outstanding technical support, teachers are empowered and students are inspired to build whatever they envision in their "mind's eye."

I COURSE DESIGN

Each lab is one semester and designed for 3-5 students. Foundations is the recommended prerequisite to the Drones Lab + Curriculum.



GEAR REDUCER

TACHOMETER

MULTIMETER

TORQUE METER

RC CONTROL

CONTROLLER

CATAPULT

FIND YOUR MINDS-i SALES REPRESENTATIVE AT:

mindsieducation.com »

info@my minds i.com »

I CURRICULUM OUTLINE - 90 HOURS

Unit 1: Introduction to MINDS-i

- 1.1 Introduction to MINDS-i
- 1.2 Student Performance Development Process
- 1.3 What is a Robot?

Unit 2: Design Engineering

- 2.1 Model for Inquiry
- 2.2 The Importance of Data
- 2.3 Parts & Purposes
- 2.4 Simple Machines

Unit 3: Variable of Force & Motion

- 3.1 Force & Motion
- 3.2 Parts & Purposes
- 3.3 Gear Ratios; Speed & Torque
- 3.4 Friction
- 3.5 Inertia

Unit 4: Software Programming; Sensors & Servos

- 4.1 Why Programming?
- 4.2 Parts & Purposes
- 4.3 Testing the Micro-controller
- 4.4 Creating the Breadboard; Servo
- 4.5 Adding to the Breadboard; Esc
- 4.6 Adding to the Breadboard; Radio Transmitter
- 4.7 Adding to the Breadboard; Ultrasound Sensor
- 4.8 Adding to the Breadboard; QTI Sensor
- 4.9 Core Syntax

Unit 5: Autonomous Robotics

- 5.1 What Makes a Robot Autonomous
- 5.2 Basic Control Structures
- 5.3 Autonomous Obstacle Avoidance
- 5.4 Line Following

Unit 6: Mechanical & Structural Engineering

- 6.1 Levers, Cams & Span
- 6.2 Structural Design
- 6.3 Robot Arm & End of Arm Tool

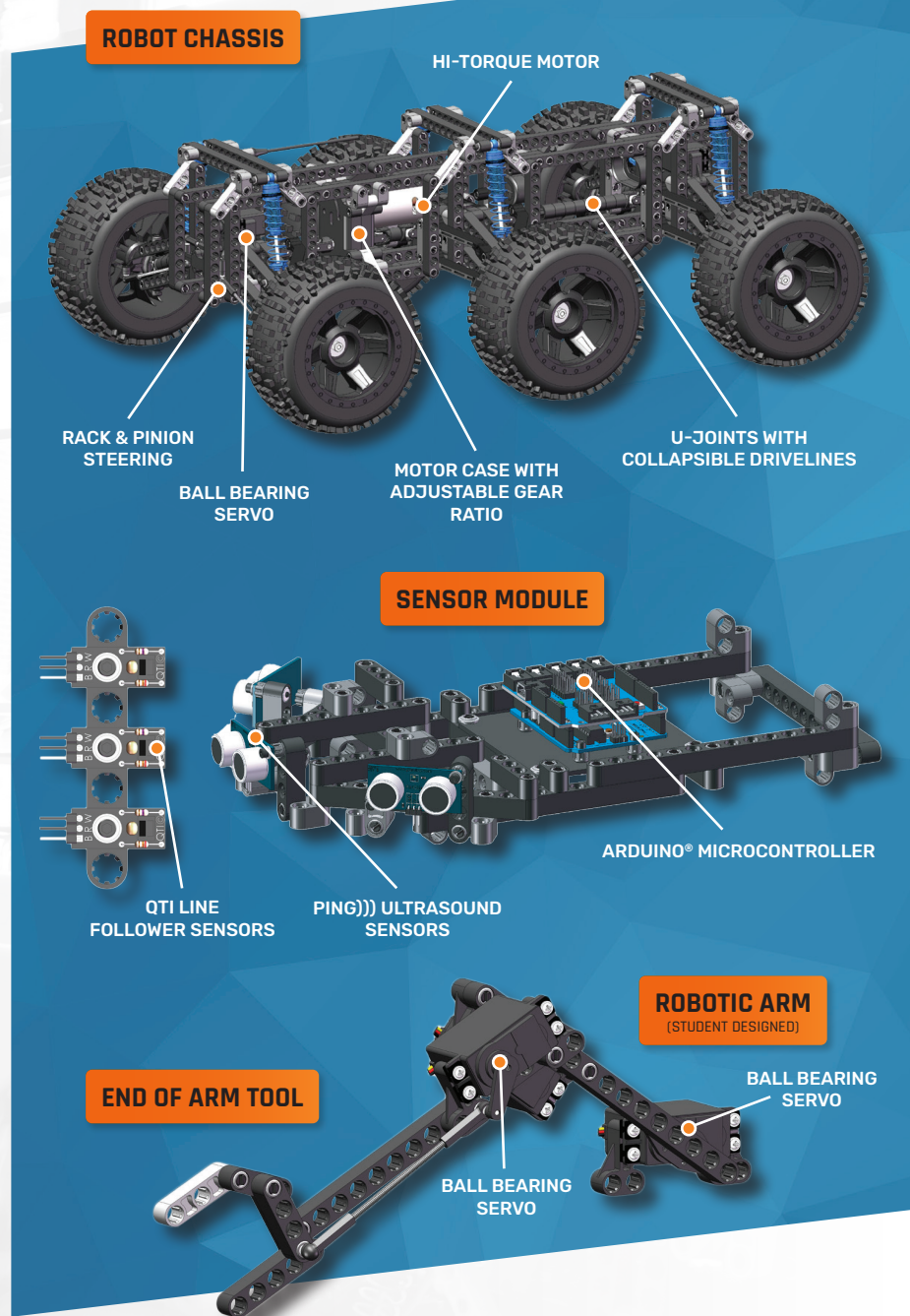
Unit 7: Culminating Project

- 7.1 Preparing for the Challenge
- 7.2 Cleanup / Organizing

STEM INTEGRATED ROBOTICS FOUNDATIONS

This curriculum covers a multitude of engineering concepts including

- » Programming
- » Physics
- » Mechanical Systems
- » Electrical and Electronic Systems
- » Hands on Activities and Capstone Projects in each Semester



ARDUINO® PROGRAMMING SOFTWARE & LEONARDO HARDWARE

- » 20 Digital I/O Pins
- » 7 PWM Channels
- » 12 Analog Input Channels (with ADC)
- » Serial & I2C Communication Ports
- » 32 KB Flash Memory & 16 MHz
- » Full Set of Sample Code in Library
- » Windows 10, OS X & Linux Ready
- » Digital Ports can Operate Servos, Motors and Sensors

```
PingSensor | Arduino 1.6.7
File Edit Sketch Tools Help
PingSensor
15 Servo drive, steez;
16
17 void setup() {
18   //set a pin for the ESC/steering servo to use
19   drive.attach(4);
20   steez.attach(5);
21
22   //set the initial throttle/direction for the ESC/servo
23   drive.write(90);
24   steez.write(90);
}
```